

# Probability Theory: Axiomatic Foundations

---

Mathematics Department

# **Lecture 1: The Sample Space and The Axiomatic Foundation**

---

# What is Probability?

- A mathematical framework for quantifying **uncertainty**.

# What is Probability?

- A mathematical framework for quantifying **uncertainty**.
- Used in almost every field: physics, finance, computer science, biology, engineering, etc.

# What is Probability?

- A mathematical framework for quantifying **uncertainty**.
- Used in almost every field: physics, finance, computer science, biology, engineering, etc.
- Today, we move from *intuitive* notions (like "chance" or "odds") to a **rigorous mathematical model**.

# The Fundamental Concept: The Sample Space

## Definition (Sample Space $\Omega$ )

The **sample space**, denoted by  $\Omega$  (Omega), is the set of all possible outcomes of a random experiment.

## Example (Coin Toss)

$\Omega = \{Heads, Tails\}$  or simply  $\Omega = \{H, T\}$ .

## Example (Rolling a Die)

$\Omega = \{1, 2, 3, 4, 5, 6\}$ .

# More Sample Space Examples

## Example (Two Coin Tosses)

What are all possible sequences?

# More Sample Space Examples

## Example (Two Coin Tosses)

What are all possible sequences?  $\Omega = \{HH, HT, TH, TT\}$ .

## Example (Waiting for a Bus)

You measure the time (in minutes) until the next bus arrives.

# More Sample Space Examples

## Example (Two Coin Tosses)

What are all possible sequences?  $\Omega = \{HH, HT, TH, TT\}$ .

## Example (Waiting for a Bus)

You measure the time (in minutes) until the next bus arrives.  
 $\Omega = \{x \in \mathbb{R} \mid x \geq 0\}$ . This is an **infinite** sample space.

# Types of Sample Spaces

Sample spaces can be:

- **Finite:**  $\Omega = \{\omega_1, \omega_2, \dots, \omega_n\}$  (Die roll, coin toss)
- **Countably Infinite:** Outcomes can be listed in a sequence (e.g.,  $\Omega = \{0, 1, 2, 3, \dots\}$  for "number of emails received in an hour")
- **Uncountably Infinite:**  $\Omega$  is a continuum (e.g.,  $\Omega = [0, 1] \subset \mathbb{R}$  for "randomly picking a point between 0 and 1")

The type of  $\Omega$  influences the mathematical tools we need.

# From Outcomes to Events

## Definition (Event)

An **event** is a subset of the sample space  $\Omega$ . We say event  $A$  *occurs* if the outcome  $\omega$  of the experiment is an element of  $A$ .

## Example (Die Roll)

Let  $\Omega = \{1, 2, 3, 4, 5, 6\}$ .

- $A = \{2, 4, 6\}$  is the event "roll an even number".
- $B = \{3\}$  is the event "roll a three" (a **simple event**).
- $C = \{1, 2, 3\}$  is the event "roll a number less than 4".

# Set Theory = The Language of Probability

Probability theory is built on set theory.

- **Union** ( $A \cup B$ ): "A or B occurs"
- **Intersection** ( $A \cap B$ ): "A and B occur"
- **Complement** ( $A^c$ ): "A does not occur"
- **Empty Set** ( $\emptyset$ ): The **impossible event** (contains no outcomes)
- **Sample Space** ( $\Omega$ ): The **certain event** (contains all outcomes)

## The Goal: Assigning probabilities

We want to assign a number  $\mathbb{P}(A)$  to any event  $A$ , called the **probability of  $A$** , that represents the "chance" it occurs.

- $\mathbb{P}(A)$  should be between 0 and 1.
- $\mathbb{P}(\Omega)$  should be 1 (something must happen!).
- For disjoint events  $A$  and  $B$ ,  $\mathbb{P}(A \cup B) = \mathbb{P}(A) + \mathbb{P}(B)$ .

But can we define  $\mathbb{P}(A)$  for every subset  $A$  of  $\Omega$ ?

## A Naive Approach: Discrete Uniform Probability

For a **finite** sample space with  $N$  **equally likely** outcomes, we can define:

$$\mathbb{P}(A) = \frac{\text{Number of outcomes in } A}{\text{Total number of outcomes } N} = \frac{|A|}{|\Omega|}$$

### Example (Fair Die)

$\Omega = \{1, 2, 3, 4, 5, 6\}$ ,  $|\Omega| = 6$ .

- $\mathbb{P}(\text{even}) = \mathbb{P}(\{2, 4, 6\}) = \frac{3}{6} = \frac{1}{2}$ .
- $\mathbb{P}(\text{roll a 3}) = \mathbb{P}(\{3\}) = \frac{1}{6}$ .

This works perfectly for finite, symmetric experiments. But what about others?

# The Need for a General Theory

The naive approach fails for:

- **Infinite Sample Spaces:** "Picking a random point in  $[0, 1]$ ." There are infinitely many points, so the probability of any single point is... 0? But the event is not impossible.
- **Biased Coins:** Outcomes are not equally likely.

We need a more powerful and general system.

# Kolmogorov's Axioms (1933)

Andrey Kolmogorov established the modern axiomatic foundation of probability.

## The Axioms

A **probability measure**  $\mathbb{P}$  is a function that assigns a number  $\mathbb{P}(A)$  to an event  $A$  such that:

1. **Non-negativity:**  $\mathbb{P}(A) \geq 0$  for any event  $A$ .
2. **Unit Measure:**  $\mathbb{P}(\Omega) = 1$ .
3. **Countable Additivity:** For any sequence of **pairwise disjoint** events  $A_1, A_2, A_3, \dots$  (i.e.,  $A_i \cap A_j = \emptyset$  for  $i \neq j$ ),

$$\mathbb{P}\left(\bigcup_{i=1}^{\infty} A_i\right) = \sum_{i=1}^{\infty} \mathbb{P}(A_i).$$

# Immediate Consequences of the Axioms

From the three axioms, we can prove many natural rules:

## Theorem

1.  $\mathbb{P}(\emptyset) = 0$ .
2.  $\mathbb{P}(A^c) = 1 - \mathbb{P}(A)$ .
3. *If  $A \subseteq B$ , then  $\mathbb{P}(A) \leq \mathbb{P}(B)$ .*
4.  $\mathbb{P}(A \cup B) = \mathbb{P}(A) + \mathbb{P}(B) - \mathbb{P}(A \cap B)$ .

These match our intuition! The power of the axioms is that these become **theorems**.

## Example: Using the Axioms and Theorems

In a city, 60% of households have a dog, 45% have a cat, and 30% have both. What is the probability a randomly selected household has...

1. a dog or a cat?

## Example: Using the Axioms and Theorems

In a city, 60% of households have a dog, 45% have a cat, and 30% have both. What is the probability a randomly selected household has...

1. a dog or a cat?

$$\mathbb{P}(D \cup C) = \mathbb{P}(D) + \mathbb{P}(C) - \mathbb{P}(D \cap C) = 0.6 + 0.45 - 0.3 = 0.75.$$

2. neither?

## Example: Using the Axioms and Theorems

In a city, 60% of households have a dog, 45% have a cat, and 30% have both. What is the probability a randomly selected household has...

1. a dog or a cat?

$$\mathbb{P}(D \cup C) = \mathbb{P}(D) + \mathbb{P}(C) - \mathbb{P}(D \cap C) = 0.6 + 0.45 - 0.3 = 0.75.$$

2. neither?  $\mathbb{P}(\text{neither}) = 1 - \mathbb{P}(D \cup C) = 1 - 0.75 = 0.25.$

# Summary: Lecture 1

- **Sample Space  $\Omega$** : The set of all possible outcomes.
- **Event**: A subset of  $\Omega$ .
- **Probability Measure  $\mathbb{P}$** : A function satisfying Kolmogorov's three axioms:
  1. Non-negativity
  2. Unit Measure ( $\mathbb{P}(\Omega) = 1$ )
  3. Countable Additivity
- From these axioms, we can derive all other rules of probability (complement rule, addition rule, etc.).

**Next Lecture:** What is the **domain** of the function  $\mathbb{P}$ ? Can we define it on *every* subset?

## **Lecture 2: $\sigma$ -algebras and Measurable Spaces**

---

## Recap and a New Question

- **Sample Space  $\Omega$ :** All possible outcomes.
- **Probability Measure  $\mathbb{P}$ :** Assigns a number to an *event* (a subset of  $\Omega$ ).
- **Axioms:**  $\mathbb{P}(A) \geq 0$ ,  $\mathbb{P}(\Omega) = 1$ , Countable additivity for disjoint events.

**Question:** For a given  $\Omega$ , on which collection of subsets (events) can we define  $\mathbb{P}$ ? **All of them?**

## The Problem: Unpleasant Subsets

For  $\Omega = [0, 1]$  (e.g., "pick a point at random"), we'd like to define  $\mathbb{P}$  for any interval. For example:

$$\mathbb{P}([a, b]) = b - a.$$

This seems natural. But can we define  $\mathbb{P}(A)$  for **every possible subset**  $A \subset [0, 1]$  and still satisfy the axioms?

# The Problem: Unpleasant Subsets

For  $\Omega = [0, 1]$  (e.g., "pick a point at random"), we'd like to define  $\mathbb{P}$  for any interval. For example:

$$\mathbb{P}([a, b]) = b - a.$$

This seems natural. But can we define  $\mathbb{P}(A)$  for **every possible subset**  $A \subset [0, 1]$  and still satisfy the axioms?

## Vitali's Theorem (1905)

No. It is **impossible** to define a probability measure  $\mathbb{P}$  on *all* subsets of  $[0, 1]$  such that  $\mathbb{P}([a, b]) = b - a$ .

We must restrict the domain of  $\mathbb{P}$  to a "nice" collection of subsets.

# The Solution: $\sigma$ -algebras

We define  $\mathbb{P}$  not on all subsets of  $\Omega$ , but on a special collection of subsets called a  $\sigma$ -algebra.

## Definition ( $\sigma$ -algebra)

A collection  $\mathcal{F}$  of subsets of  $\Omega$  is called a  $\sigma$ -algebra if it satisfies:

1. Contains Sample Space:  $\Omega \in \mathcal{F}$ .
2. Closed under Complement: If  $A \in \mathcal{F}$ , then  $A^c \in \mathcal{F}$ .
3. Closed under Countable Unions: If  $A_1, A_2, A_3, \dots \in \mathcal{F}$ , then  $\bigcup_{i=1}^{\infty} A_i \in \mathcal{F}$ .

The pair  $(\Omega, \mathcal{F})$  is called a measurable space.

## Why these three rules?

The axioms of a  $\sigma$ -algebra are perfectly matched to the axioms of probability.

- Axiom 1 ( $\Omega \in \mathcal{F}$ ): We need to define  $\mathbb{P}(\Omega) = 1$ .
- Axiom 2 (Closed under complement): We need to define  $\mathbb{P}(A^c)$  if we know  $\mathbb{P}(A)$ .
- Axiom 3 (Closed under countable unions): We need to define  $\mathbb{P}(\bigcup A_i)$  for disjoint events (Axiom 3 of probability).

A  $\sigma$ -algebra is the **domain** of a probability measure. It is the collection of "measurable events".

# Simple Examples of $\sigma$ -algebras

## Example (The Trivial $\sigma$ -algebra)

For any  $\Omega$ , the smallest possible  $\sigma$ -algebra is  $\mathcal{F} = \{\emptyset, \Omega\}$ .

## Example (The Power Set)

For any  $\Omega$ , the largest possible  $\sigma$ -algebra is the **power set**  $\mathcal{P}(\Omega)$ , the set of *all* subsets.

For finite or countably infinite  $\Omega$ , we can usually use  $\mathcal{F} = \mathcal{P}(\Omega)$  without issues. The problems arise with uncountable  $\Omega$  (like  $[0, 1]$ ).

## A More Interesting Example

Let  $\Omega = \{a, b, c, d\}$  (a finite sample space). Is this a  $\sigma$ -algebra?

$$\mathcal{F} = \{\emptyset, \{a, b\}, \{c, d\}, \Omega\}$$

## A More Interesting Example

Let  $\Omega = \{a, b, c, d\}$  (a finite sample space). Is this a  $\sigma$ -algebra?

$$\mathcal{F} = \{\emptyset, \{a, b\}, \{c, d\}, \Omega\}$$

Let's check the axioms:

1.  $\Omega \in \mathcal{F}$ ? ✓
2. Closed under complement?
  - $\emptyset^c = \Omega \in \mathcal{F}$  ✓
  - $\{a, b\}^c = \{c, d\} \in \mathcal{F}$  ✓
  - $\{c, d\}^c = \{a, b\} \in \mathcal{F}$  ✓
  - $\Omega^c = \emptyset \in \mathcal{F}$  ✓
3. Closed under countable unions? (e.g.,  $\{a, b\} \cup \{c, d\} = \Omega \in \mathcal{F}$ ) ✓

Yes,  $\mathcal{F}$  is a  $\sigma$ -algebra. It has "2 events" of size 2.

# Generated $\sigma$ -algebra

Often, we start with a collection of "simple" events we care about (e.g., all intervals in  $[0, 1]$ ) and then **generate** the smallest  $\sigma$ -algebra that contains them.

## Definition (Borel $\sigma$ -algebra)

For  $\Omega = \mathbb{R}$ , the **Borel  $\sigma$ -algebra**  $\mathcal{B}(\mathbb{R})$  is the  $\sigma$ -algebra generated by all open intervals  $(a, b)$ .

- It contains all intervals (open, closed, half-open), single points, countable sets, and much more.
- It excludes the "pathological" sets that cause problems.
- This is the standard  $\sigma$ -algebra used for  $\mathbb{R}$  and its subsets.

# The Triple $(\Omega, \mathcal{F}, \mathbb{P})$

We now have the three components of a probability model:

## Probability Space

A **probability space** is a triple  $(\Omega, \mathcal{F}, \mathbb{P})$  consisting of:

1. A **sample space**  $\Omega$ .
2. A  **$\sigma$ -algebra**  $\mathcal{F}$  of subsets of  $\Omega$  (the measurable events).
3. A **probability measure**  $\mathbb{P}$  on  $\mathcal{F}$  satisfying Kolmogorov's axioms.

This is the rigorous mathematical foundation for all of probability theory.

## Visualizing a Probability Space

Think of it as a unit mass (total probability = 1) spread over the sample space  $\Omega$ . The  $\sigma$ -algebra  $\mathcal{F}$  tells us which chunks of this mass we are allowed to "measure".  $\mathbb{P}(A)$  is the mass contained in the event  $A$ .

## Example 1: Finite Space (Fair Die)

- $\Omega = \{1, 2, 3, 4, 5, 6\}$
- $\mathcal{F} = \mathcal{P}(\Omega)$  (the power set, all 64 subsets)
- For any  $A \in \mathcal{F}$ ,  $\mathbb{P}(A) = \frac{|A|}{6}$

Let's verify an axiom. Let  $A = \{1\}$  and  $B = \{2\}$ . They are disjoint.

$$\mathbb{P}(A \cup B) = \mathbb{P}(\{1, 2\}) = \frac{2}{6} = \frac{1}{3}.$$

$$\mathbb{P}(A) + \mathbb{P}(B) = \frac{1}{6} + \frac{1}{6} = \frac{1}{3}. \quad \checkmark$$

$(\Omega, \mathcal{F}, \mathbb{P})$  is a valid probability space.

## Example 2: Infinite Space (Uniform on $[0, 1]$ )

- $\Omega = [0, 1]$
- $\mathcal{F} = \mathcal{B}([0, 1])$  (the Borel sets on  $[0, 1]$ )
- For an interval  $I = [a, b] \subset [0, 1]$ , we define  $\mathbb{P}(I) = b - a$ .

This definition is extended to all sets in  $\mathcal{F}$  in a consistent way that satisfies the countable additivity axiom. We cannot define it for sets outside  $\mathcal{F}$ .

## Why Bother with $\sigma$ -algebras?

- **Mathematical Necessity:** They resolve the theoretical problem of defining measures on uncountable spaces. They are the "domain" of  $\mathbb{P}$ .

# Why Bother with $\sigma$ -algebras?

- **Mathematical Necessity:** They resolve the theoretical problem of defining measures on uncountable spaces. They are the "domain" of  $\mathbb{P}$ .
- **Modeling Information:** Different  $\sigma$ -algebras represent different **levels of information**. (We will see this in conditional expectation and martingales later).

# Why Bother with $\sigma$ -algebras?

- **Mathematical Necessity:** They resolve the theoretical problem of defining measures on uncountable spaces. They are the "domain" of  $\mathbb{P}$ .
- **Modeling Information:** Different  $\sigma$ -algebras represent different **levels of information**. (We will see this in conditional expectation and martingales later).
- **Foundational:** All advanced probability (stochastic processes, modern statistics) relies on this framework.

## Summary: Lecture 2

- We **cannot** define a probability measure on *all* subsets of an uncountable  $\Omega$ .
- The solution is to define  $\mathbb{P}$  on a  **$\sigma$ -algebra**  $\mathcal{F}$ .
- A  **$\sigma$ -algebra** is a collection of subsets closed under complement and countable unions.
- The Borel  $\sigma$ -algebra on  $\mathbb{R}$  is the most important example.
- A **probability space** is the triple  $(\Omega, \mathcal{F}, \mathbb{P})$ .

**Next Lecture:** How do we actually *construct* and *work with* probability measures?

# **Lecture 3: Constructing Probability Measures**

---

## Recap: The Probability Space

We model randomness with a triple  $(\Omega, \mathcal{F}, \mathbb{P})$ .

- $\Omega$ : Sample Space (what can happen?)
- $\mathcal{F}$ :  $\sigma$ -algebra (what questions can we ask?)
- $\mathbb{P}$ : Probability Measure (what are the answers?)

**Today's Question:** How do we actually **define** or **construct** the probability measure  $\mathbb{P}$ ? We can't just list  $\mathbb{P}(A)$  for every  $A \in \mathcal{F}$ .

# The Strategy: Start Simple

We often know how to assign probability to "simple" events.

- **Die Roll:** For each simple event  $\{i\}$ ,  $\mathbb{P}(\{i\}) = 1/6$ .
- **Uniform on  $[0, 1]$ :** For an interval  $[a, b]$ , we want  $\mathbb{P}([a, b]) = b - a$ .

The collection of these "simple" events (e.g., all intervals) is often not a  $\sigma$ -algebra itself. We call it a **generator**.

# From the Generator to the $\sigma$ -algebra

We have:

1. A collection of "simple" sets  $\mathcal{C}$  (the generator) where we know  $\mathbb{P}$ .
2. The full  $\sigma$ -algebra  $\mathcal{F} = \sigma(\mathcal{C})$  generated by  $\mathcal{C}$ .

**Key Problem:** Does our definition of  $\mathbb{P}$  on the small collection  $\mathcal{C}$  extend **uniquely** to the large  $\sigma$ -algebra  $\mathcal{F}$ ?

## Carathéodory's Extension Theorem

Yes, under certain conditions. If  $\mathbb{P}$  is well-behaved on  $\mathcal{C}$  (e.g., it is **countably additive** on it), then it extends uniquely to a probability measure on  $\sigma(\mathcal{C})$ .

This theorem is the workhorse behind constructing probability measures.

## Construction 1: Discrete Probability Spaces

This is the simplest case. Let  $\Omega$  be finite or countably infinite:

$$\Omega = \{\omega_1, \omega_2, \omega_3, \dots\}.$$

1. Define a **probability mass function (pmf)**  $p : \Omega \rightarrow [0, 1]$  such that  $\sum_i p(\omega_i) = 1$ .
2. For any subset  $A \in \mathcal{F} = \mathcal{P}(\Omega)$ , define:

$$\mathbb{P}(A) = \sum_{\omega_i \in A} p(\omega_i)$$

This construction *automatically* satisfies Kolmogorov's axioms (check countable additivity!).

## Discrete Example: Poisson Distribution

Model: "Number of emails received in an hour."

- $\Omega = \{0, 1, 2, 3, \dots\}$
- $\mathcal{F} = \mathcal{P}(\Omega)$  (all subsets)
- For a parameter  $\lambda > 0$ , the pmf is  $p(k) = e^{-\lambda} \frac{\lambda^k}{k!}$  for  $k = 0, 1, 2, \dots$
- For any event  $A$ , e.g.,  $A = \{\text{even numbers}\} = \{0, 2, 4, 6, \dots\}$ ,

$$\mathbb{P}(A) = \sum_{k \text{ even}} e^{-\lambda} \frac{\lambda^k}{k!} = e^{-\lambda} \cosh(\lambda).$$

The axioms are satisfied because we've defined  $\mathbb{P}$  by a summable series.

## Construction 2: Continuous Probability Spaces

Let  $\Omega = \mathbb{R}$  (or a subset). We use **probability density functions (pdfs)**.

1. Find a function  $f : \mathbb{R} \rightarrow [0, \infty)$  such that  $\int_{-\infty}^{\infty} f(x) dx = 1$ .
2. For any event  $A$  in the Borel  $\sigma$ -algebra (e.g., an interval, a union of intervals), define:

$$\mathbb{P}(A) = \int_A f(x) dx$$

This construction also satisfies the axioms (e.g., countable additivity comes from properties of the Lebesgue integral).

## Continuous Example: Uniform Distribution

Model: "Pick a random point between 1 and 5."

- $\Omega = [1, 5]$
- $\mathcal{F} = \mathcal{B}([1, 5])$
- The pdf is:

$$f(x) = \begin{cases} \frac{1}{4} & \text{for } 1 \leq x \leq 5 \\ 0 & \text{otherwise} \end{cases}$$

- What is  $\mathbb{P}([2, 3])$ ?  $\mathbb{P}([2, 3]) = \int_2^3 \frac{1}{4} dx = \frac{1}{4}(3 - 2) = \frac{1}{4}$ .
- What is  $\mathbb{P}(\{2.5\})$ ?  $\mathbb{P}(\{2.5\}) = \int_{2.5}^{2.5} f(x) dx = 0$ .

Probability zero is not the same as impossible!

# A Mix of Both: The CDF

There is a unified way to describe *any* probability measure on  $\mathbb{R}$ .

## Definition (Cumulative Distribution Function (CDF))

The **CDF** of a probability measure  $\mathbb{P}$  is the function  $F : \mathbb{R} \rightarrow [0, 1]$  defined by:

$$F(x) = \mathbb{P}((-\infty, x])$$

## Theorem

*A function  $F$  is a CDF for some  $\mathbb{P}$  if and only if:*

1.  *$F$  is non-decreasing.*
2.  *$F$  is right-continuous.*
3.  *$\lim_{x \rightarrow -\infty} F(x) = 0$  and  $\lim_{x \rightarrow \infty} F(x) = 1$ .*

## Example (Fair Die (Discrete))

$F(x)$  is a step function.

**Example (Uniform on  $[1, 5]$ )**

*(Continuous)]  $F(x)$  is a piecewise linear function.*

## Putting It All Together: A Complete Example

**Experiment:** Toss a fair coin. If Heads, roll a 4-sided die. If Tails, roll a 6-sided die. What is  $\mathbb{P}(\text{roll a } 3)$ ?

## Putting It All Together: A Complete Example

Experiment: Toss a fair coin. If Heads, roll a 4-sided die. If Tails, roll a 6-sided die. What is  $\mathbb{P}(\text{roll a } 3)$ ?

1. **Construct  $\Omega$ :**  $\Omega = \{H1, H2, H3, H4, T1, T2, T3, T4, T5, T6\}$ .

## Putting It All Together: A Complete Example

Experiment: Toss a fair coin. If Heads, roll a 4-sided die. If Tails, roll a 6-sided die. What is  $\mathbb{P}(\text{roll a } 3)$ ?

1. **Construct  $\Omega$ :**  $\Omega = \{H1, H2, H3, H4, T1, T2, T3, T4, T5, T6\}$ .
2. **Construct  $\mathcal{F}$ :**  $\mathcal{F} = \mathcal{P}(\Omega)$ .

## Putting It All Together: A Complete Example

Experiment: Toss a fair coin. If Heads, roll a 4-sided die. If Tails, roll a 6-sided die. What is  $\mathbb{P}(\text{roll a } 3)$ ?

1. **Construct  $\Omega$ :**  $\Omega = \{H1, H2, H3, H4, T1, T2, T3, T4, T5, T6\}$ .
2. **Construct  $\mathcal{F}$ :**  $\mathcal{F} = \mathcal{P}(\Omega)$ .
3. **Assign probabilities:** The outcomes are **not** equally likely!
  - $\mathbb{P}(\{H_i\}) = \frac{1}{2} \cdot \frac{1}{4} = \frac{1}{8}$  for  $i = 1, 2, 3, 4$ .
  - $\mathbb{P}(\{T_j\}) = \frac{1}{2} \cdot \frac{1}{6} = \frac{1}{12}$  for  $j = 1, \dots, 6$ .

## Putting It All Together: A Complete Example

Experiment: Toss a fair coin. If Heads, roll a 4-sided die. If Tails, roll a 6-sided die. What is  $\mathbb{P}(\text{roll a 3})$ ?

1. **Construct  $\Omega$ :**  $\Omega = \{H1, H2, H3, H4, T1, T2, T3, T4, T5, T6\}$ .
2. **Construct  $\mathcal{F}$ :**  $\mathcal{F} = \mathcal{P}(\Omega)$ .
3. **Assign probabilities:** The outcomes are **not** equally likely!
  - $\mathbb{P}(\{H_i\}) = \frac{1}{2} \cdot \frac{1}{4} = \frac{1}{8}$  for  $i = 1, 2, 3, 4$ .
  - $\mathbb{P}(\{T_j\}) = \frac{1}{2} \cdot \frac{1}{6} = \frac{1}{12}$  for  $j = 1, \dots, 6$ .
4. **Define  $\mathbb{P}$  for any event:** For  $A = \{\text{roll a 3}\} = \{H3, T3\}$ ,

$$\mathbb{P}(A) = \mathbb{P}(\{H3\}) + \mathbb{P}(\{T3\}) = \frac{1}{8} + \frac{1}{12} = \frac{5}{24}.$$

# Summary of the Three Lectures

- **Lecture 1:** We want to assign numbers to events. Kolmogorov's Axioms give the rules. ( $\mathbb{P}(A) \geq 0$ ,  $\mathbb{P}(\Omega) = 1$ , countable additivity).
- **Lecture 2:** We can't define  $\mathbb{P}$  on all subsets. We restrict its domain to a " $\sigma$ -algebra"  $\mathcal{F}$  of measurable events. This gives us a **probability space**  $(\Omega, \mathcal{F}, \mathbb{P})$ .
- **Lecture 3:** We construct  $\mathbb{P}$  by first defining it on a simple collection of sets (using pmfs, pdfs, or direct assignment) and then using extension theorems to define it on the entire  $\sigma$ -algebra.

# Where to go from here?

You now have the rigorous foundation to explore:

- **Random Variables:** Functions  $X : \Omega \rightarrow \mathbb{R}$  that translate outcomes into numbers.
- **Distribution:** The probability measure induced by  $X$  on  $\mathbb{R}$ .
- **Expectation:** The "average" value of a random variable.
- **Limit Theorems:** The Law of Large Numbers and the Central Limit Theorem.

Congratulations! You have built the bedrock of modern probability theory.